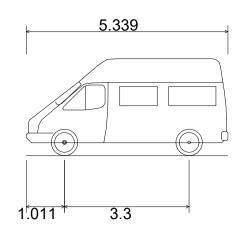


STANDARD DESIGN VEHICLE PROFILE SCALE 1:10



3.5t Panel Van
Overall Length
Overall Width
Overall Body Height
Min Body Ground Clearance
Track Width
Lock to lock time
Kerb to Kerb Turning Radius

Health & Safety CDM regulations 2015

Significant risks associated with this drawing are identified below and, where applicable, at specific locations on the drawing. Refer to the CDM Regulation 9 Risk Register for full details.

DO NOT CONSTRUCT FROM THIS DRAWING, TO BE USED FOR PRICING / TENDER ONLY

GENERAL NOTES:

1) DO NOT SCALE FROM THIS DRAWING

DO NOT SCALE FROM THIS DRAWING
 UNLESS NOTED OTHERWISE, LEVELS (AOD) AND COORDINATES (RELATIVE TO ORDNANCE DATUM) ARE IN METRES.
 PENDING ADDITIONAL CONFIRMATION OF VEHICLE TYPE FOR SWITCH GEAR TRANSPORT TO CONFIRM ACCESSES TO HARDSTANDING AREAS OF GIS BUILDING.

LEGEND:

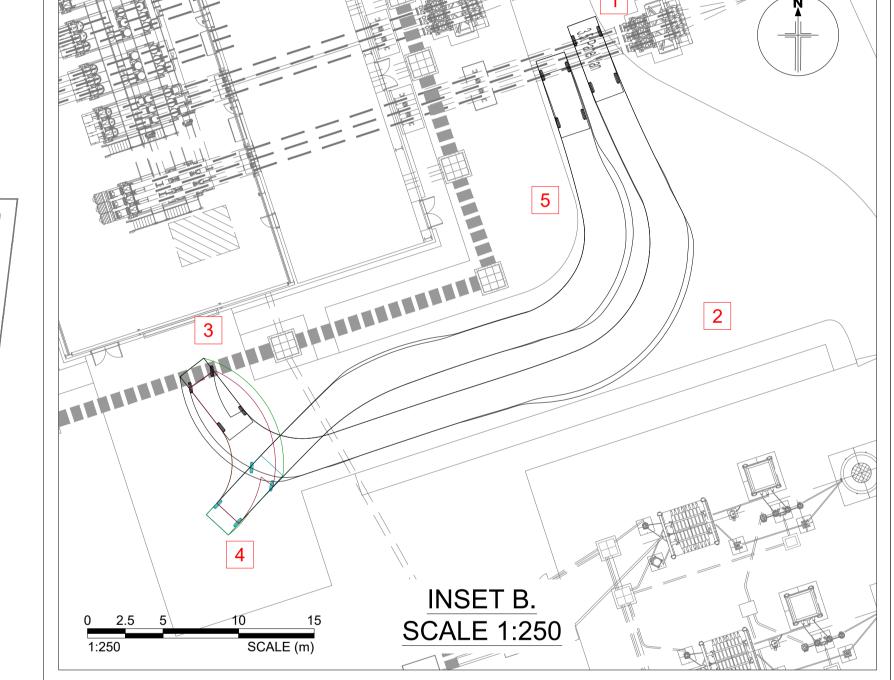
5.339m 1.986m 2.565m 0.338m 1.986m 4.00s

6.400m



DENOTES VEHICLE ROUTE ORDER

DENOTES RED LINE BOUNDARY



ASSOCIATED DRAWINGS:

- MARPT-BHK-01-ZZ-DG-C-161006 (16_LOR_0690) MARGAM SURFACING LAYOUT SHEET 01 OF 01
- MARPT-BHK-01-ZZ-DG-C-161007 (16_LOR_0691) MARGAM KERBS AND FOOTPATHS LAYOUT SHEET 01 OF 01
- MARPT-BHK-01-ZZ-DG-C-161017 (16_LOR_0697) MARGAM CIVIL
- CONSTRUCTION DETAILS SHEET 02 OF 06
- MARPT-BHK-01-ZZ-DG-C-161029 (16_LOR_0704) MARGAM SWEPT PATH ANALYSIS LAYOUT SHEET 01 OF 02
- MARPT-BHK-01-ZZ-DG-C-161030 (16_LOR_0705) MARGAM SWEPT PATH ANALYSIS LAYOUT SHEET 02 OF 02

P03	S3 - FOR REVIEW AND COMMENT	TG	CE / JD	30/05/2025
P02	S3 - FOR REVIEW AND COMMENT	TG	CE / RC	01/04/2025
P01	FOR PLANNING	KA	CE / RC	05/02/2025

Cre'd Chk'd / App'd Date

nationalgrid

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Master Scheme No:	Sub-Scheme No:	Site:
101677		MARGAM / PORT TALBOT

Scheme Name:

MARGAM CONNECTION

Document Title:

Rev Description

MARGAM SWEPT PATH ANALYSIS LAYOUT

KA 05/02/2025 27/01/2025 04/02/2025 Development Eng: Document Type: Scale: DWG AS SHOWN A1 01 OF 02 P03

SHEET 01 OF 02

National Grid Document Number: 16_LOR_0704

MARPT-BHK-01-ZZ-DG-C-161029

PRELIMINARY

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PLAN VIEW

SCALE 1:500

-5

REFER TO INSET A FOR -PARKING SWEPT PATH

ANALYSIS

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MSC1 COMPOUND